

# Team Information



Name of vehicles:

Okurosa, Somarosa

Name of team leader: Libor Přeučil

Team Name: CTU

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Team Description: The team is composed of a robot and roboticists of department of cybernetics, Czech Technical University in Prague, Faculty of Electrical Engineering.

The vehicles are based on P3AT and MMP5 commercial platforms and a embedded navigation system developed at the CTU. The navigation system relies on GPU-based image processing coupled to dead-reckoning techniques. Similar navigation system is used with other robotic platforms and AR-drone autonomous quadrotor helicopters.

Sponsors: CTU-FEE

Selection of scenario: Mule

Proof of citizenship: Czech, inside EU.