

Team Information

Picture of vehicle:



Name of vehicle: RAVON (Robust Autonomous Vehicle for Off-road Navigation)

Picture of team leader:



Name of team leader: Prof. Dr. Karsten Berns
Team Name: RAVON
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Team Information

Team Description:

The RAVON Team is part of the Robotics Research Lab at the University of Kaiserslautern. The work group was founded in April 2003. Today, 15 research assistants work under the leadership of Prof. Dr. Karsten Berns.

The outdoor platform developed in the lab is called RAVON (Robust Autonomous Vehicle for Offroad Navigation – see <http://agrosy.informatik.uni-kl.de/en/robots/ravon/>) and is based on the RobuCar TT platform by robosoft (<http://www.robosoft.fr/>). The vehicle's battery-driven 4WD utilises four independent motors. The front and rear axes can be controlled independently by linear motors to allow for advanced steering manoeuvres. As visual sensor systems, three 2D Sick (<http://www.sick.de/de/de.html>) laser scanners and two custom-built stereo camera heads have been mounted. For localisation purposes an inertial measurement unit, a magnetic field sensor, and two GPS receivers have been integrated with the vehicle's odometry. Equipped with three industrial PCs, the robot is able to move fully autonomously.

The robot's behaviour-based control system is implemented based on the open source C++ control software framework MCA2-KL (Modular Controller Architecture 2, Kaiserslautern Branch – see <http://rrlib.informatik.uni-kl.de/>) which is being developed in our working group.

The development of RAVON was started in the year 2004. Currently the vehicle realizes several behaviours guiding it through rough terrain on different test courses.

Sponsors:

DSM Computer

<http://www.dsm-computer.de>

Hankook Tire

<http://www.hankooktire-eu.com/>

Ingenieurbetrieb Kunze – Hochfrequenztechnik

http://www.ikhf.de/index_en.html

ITT Cannon

<http://www.ittcannon.com/>

Johannes Hübner Giessen

<http://www.huebner-giessen.com/>

John Deere

<http://www.deere.com/>

Mayser Polymer Electric

<http://www.mayser.com/>

MiniTec

<http://www.minitec.de/>

Team Information

Mobotix

<http://www.mobotix.com/>

Optima Batteries

<http://www.optimabatteries.com/>

SICK AG

<http://www.sick.com/home/en.html>

Unitek Industrie Elektronik

<http://www.unitek-online.de/>

Werkzeug Schmidt GmbH

<http://www.werkzeug-schmidt.de/>

Selection of scenario:

1. Reconnaissance and surveillance – Approach _X_
2. Reconnaissance and surveillance – RSTA _X_
3. Transport – Movements _X_
4. Transport – Mule _X_
5. Reconnaissance and surveillance -EOR / CRNE ____

Proof of citizenship: